



Open Innovation en PME : Cas d'applications avec BA Systèmes, fabricant de robots mobiles

Journées du groupe thématique transverse AUM
de l'Association Française de Mécanique (AFM) 2014

Outline :

1 - BA SYSTEMES
French AGV manufacturer

2 - INNOVATION
Specific model & organisation

3 - BA ROBOTICS
cases of mobile robots developments

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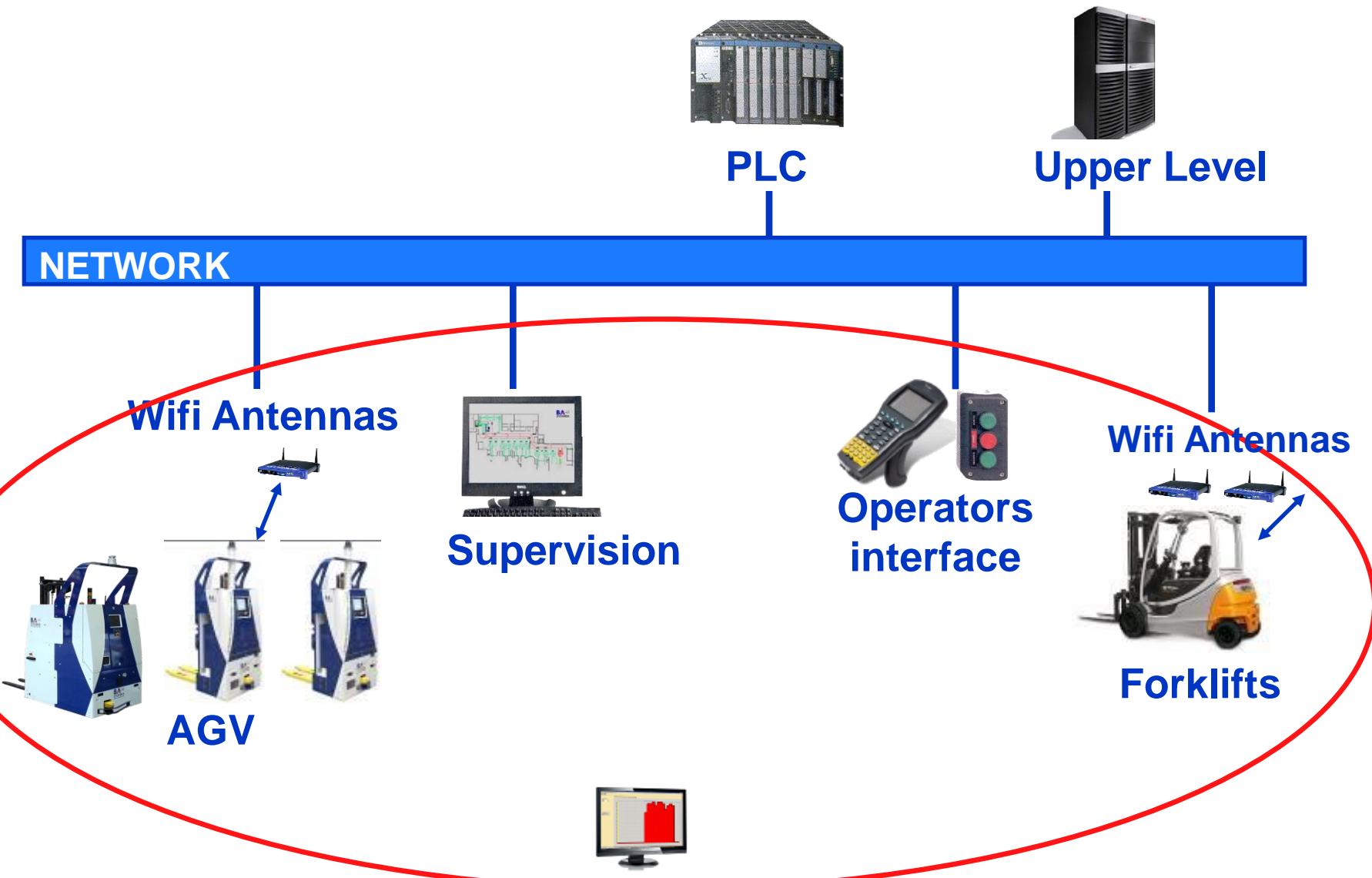
5 cases of mobile robots

BA SYSTEMES overview



- European leader in intralogistics automated systems
- Automated Guided Vehicles (AGV) & supervision system
- 35 years of experience
- Vertical business activity
- 150 employees (50% of engineers and PhD)
- 20 ME of Turnover
- 15% of turnover in R&D
Special SME adapted method to spread innovation

ROBOTIC SYSTEM



Fully manufactured AGV



Skills involved:

- Mechanical
- Electronics
- Electricity
- Software
- Communication
- Optimisation
- Project Management

Reliability : 99,7%
Life : 50 000 Hours

Mobile robot supervisor

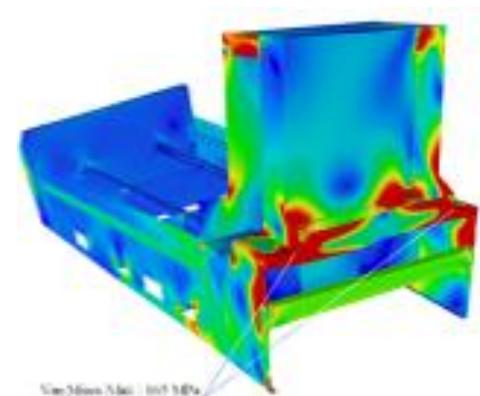
Software AGV Manager ©

- Missions assignment
- Traffic management
- Communication
- Synoptic layout
- Analysis
 - Replay
 - Production indicator
 - Reliability indicator
 - ...



Skills and resources

Resources	<ul style="list-style-type: none"> - Plan with 5 000 m² of workflow - Organization and innovation methods (LEAN) - Patents portfolio
Skills	<ul style="list-style-type: none"> - Mobile Robot : design and manufacturing - Software : specification and development - Technical and research projects management - Maintenance and retrofit of robots



AGV fleet supervision
 → Software development

A LARGE CLIENTS PORTOFOLIO

Paper / Press / Printers



Packaging



Pharmacy / Cosmetics



Agri-food



Industries



From Classic
Industrial
Activities



By using
management model

To New
Robotics
Application



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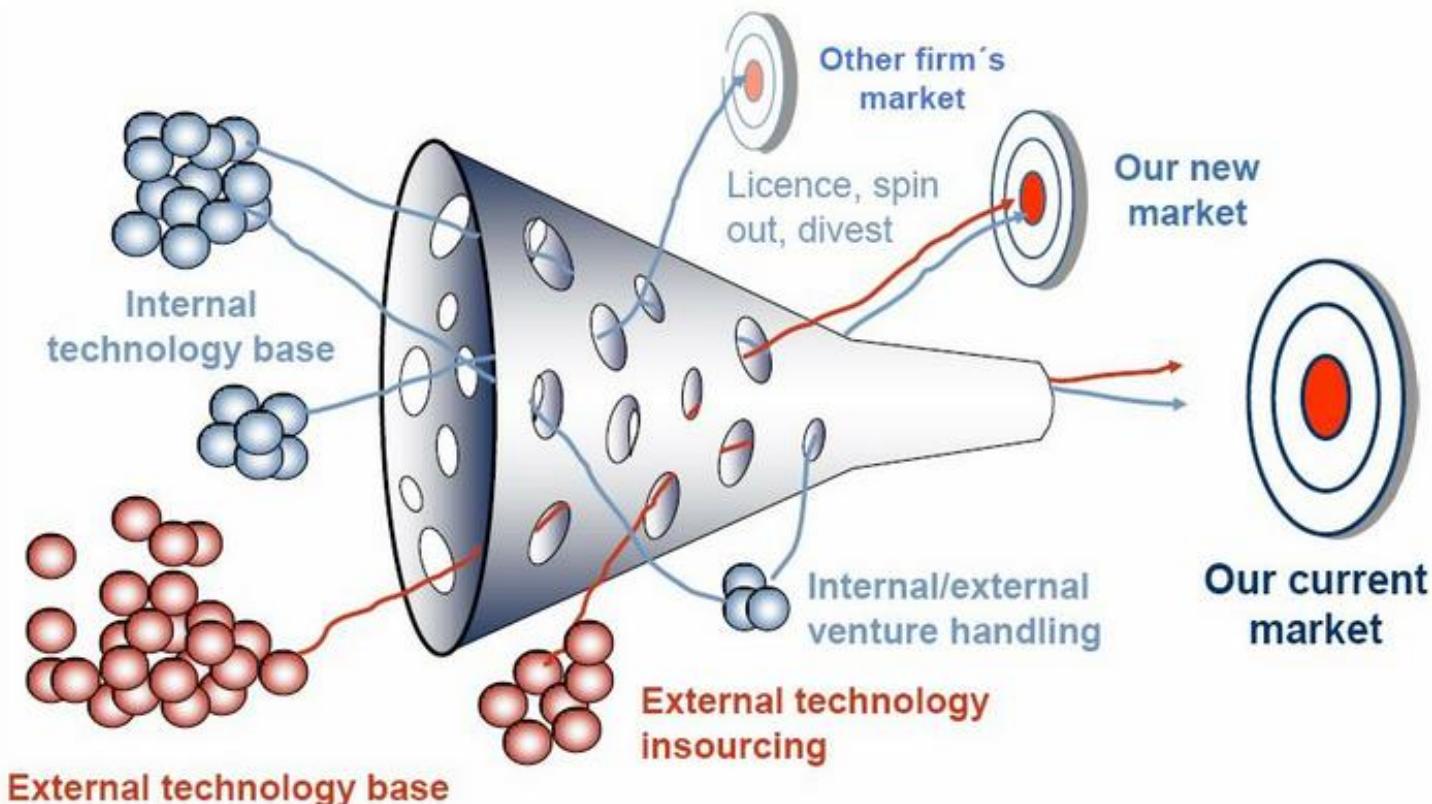
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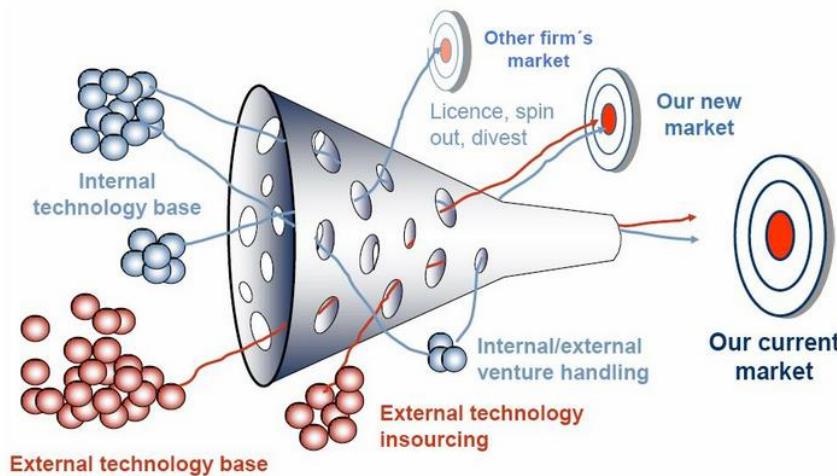
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Open innovation model



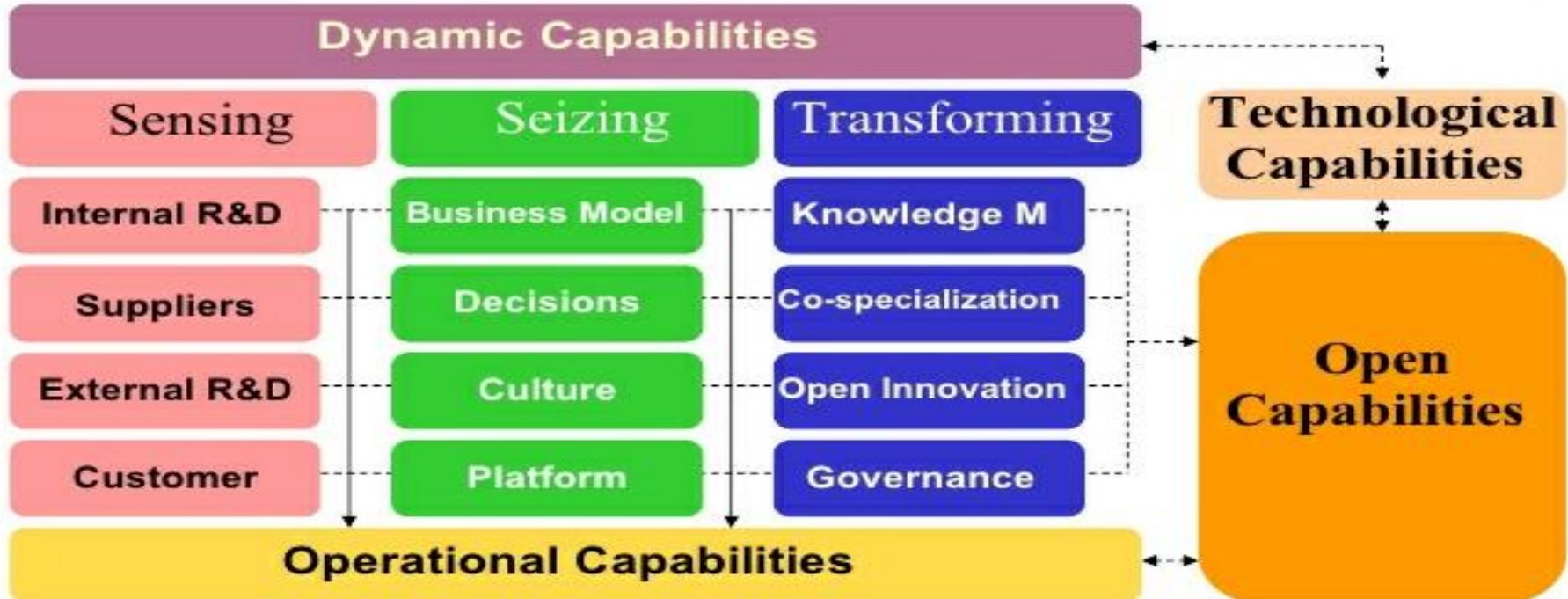
“Open innovation is the use of purposive inflows and outflows of knowledge to accelerate internal innovation, and expand the markets for external use of innovation, respectively.”

OI model Implementation



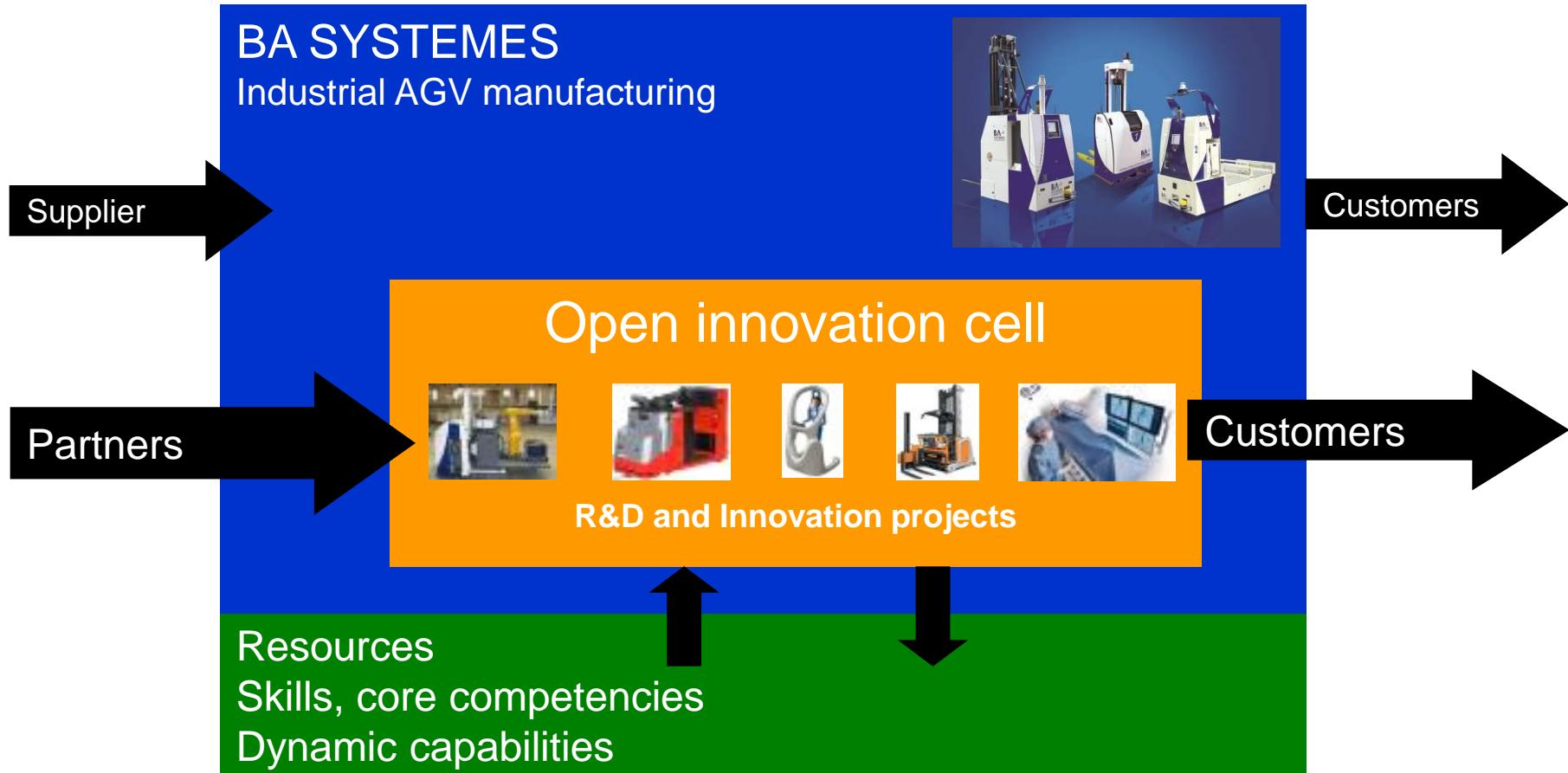
Projets industriels	B to B (triangle) Appuis techniques et scientifiques Adressage de nouveaux usages
Projets collaboratifs	FP7, ANR, FUI, RAPID, ADEME, IRT Financement partiel Absorption interne de connaissances
Projets pédagogiques	Etudes sur projets internes, Projets collaboratifs de recherche, Machines spéciales

Dynamic capabilities



Teece David J. 2007 - Explicating dynamic capabilities: the nature and microfoundations of (sustainable) enterprise performance

Internal specific organization to boost open innovation



Purposes:

- Enrichment of skills and knowledge
- Creation of new added-values
- Openness in R&D

Dedicated process for Open Innovation

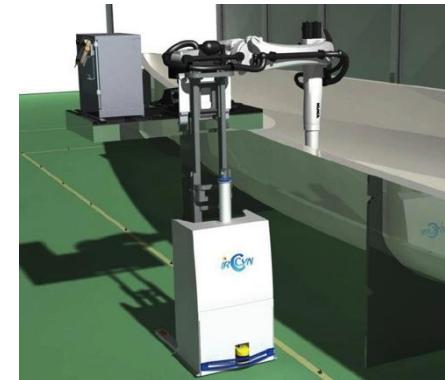
Professional Networks

- Facilitators
- Companies
- Education
- BA Systèmes
- Research



New mobile robots

BA
SYSTEMES
solutions in motion



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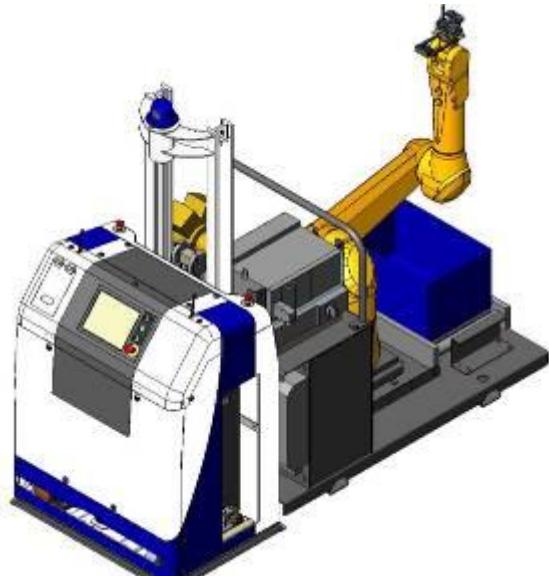
1 – AGV + robot 6 axes

Recherche > marché

Open innovation

Histoire

ROBM@RKET: 1st open innovation project



- **Mobile robot to automate picking**
- **3-year project**
Project budget: €1.7M
- **4 partners**
BA Systèmes, CEA List, IRISA-INRIA, University of Caen
- The Robm@rket project obtained **the 2009 « Innovation Supply Chain » award**.
- **Robm@rket generated several spinoffs such as:**
Discovery, ROBY, Artémis AGV...

ROBY: the automated building system



- **Mobile robot to automate drilling, sanding or bushing hammering walls**

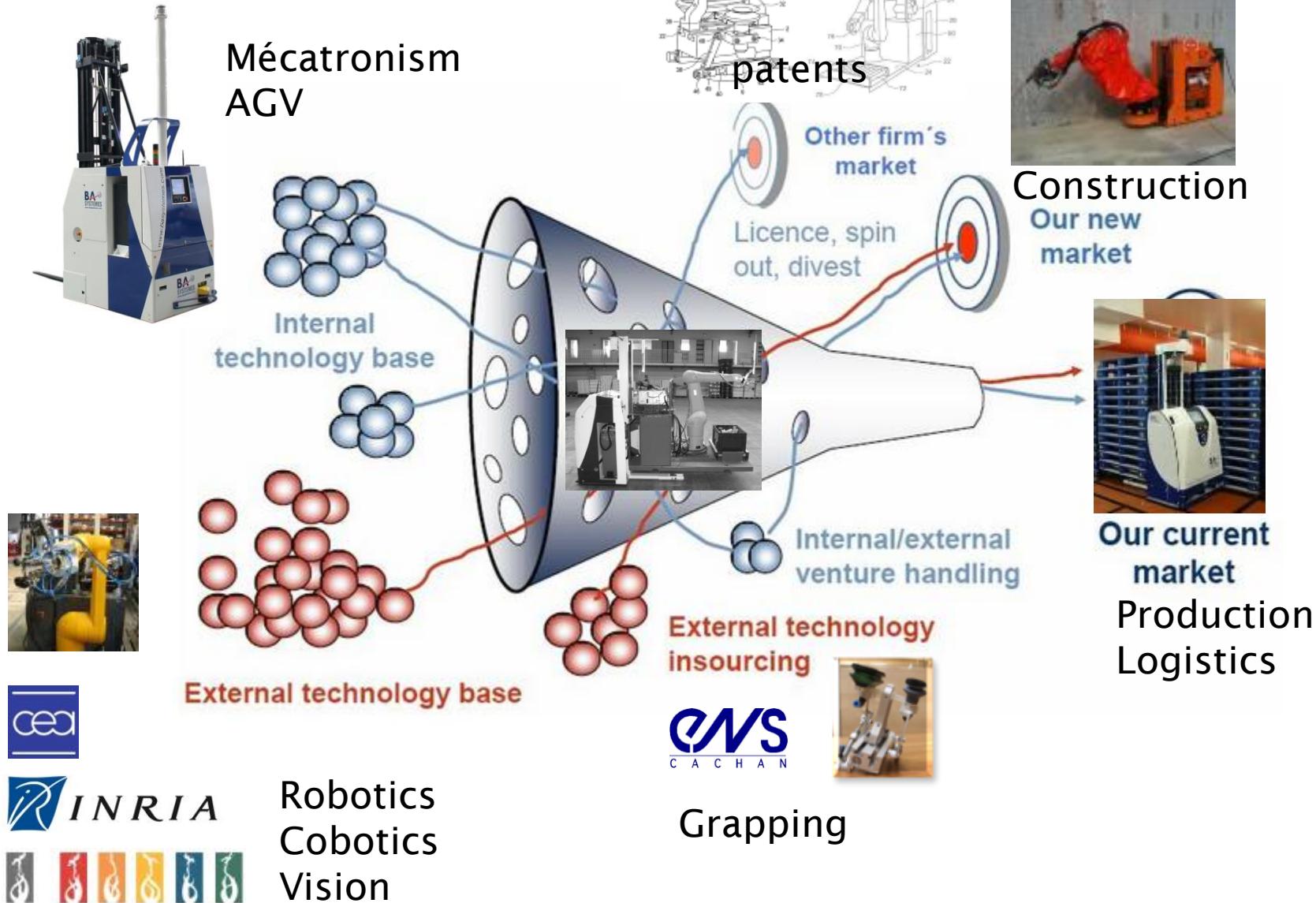
RSI* suppression, better efficiency, insures the repeatability & quality

- **Co-developed with BOUYGUES Travaux Publics**

Direct spin-off from Robm@rket:
AGV base + robotic arm

*Repetitive Strain Injury

Model implementation



AGV et robot polyarticulé le sujet n'est pas nouveau !



1991-1993

Projet STAUBLI, CEA LIST et BA SYSTEMES

2 – Apport de briques techniques

ROB@GRO: automatic feeding robot

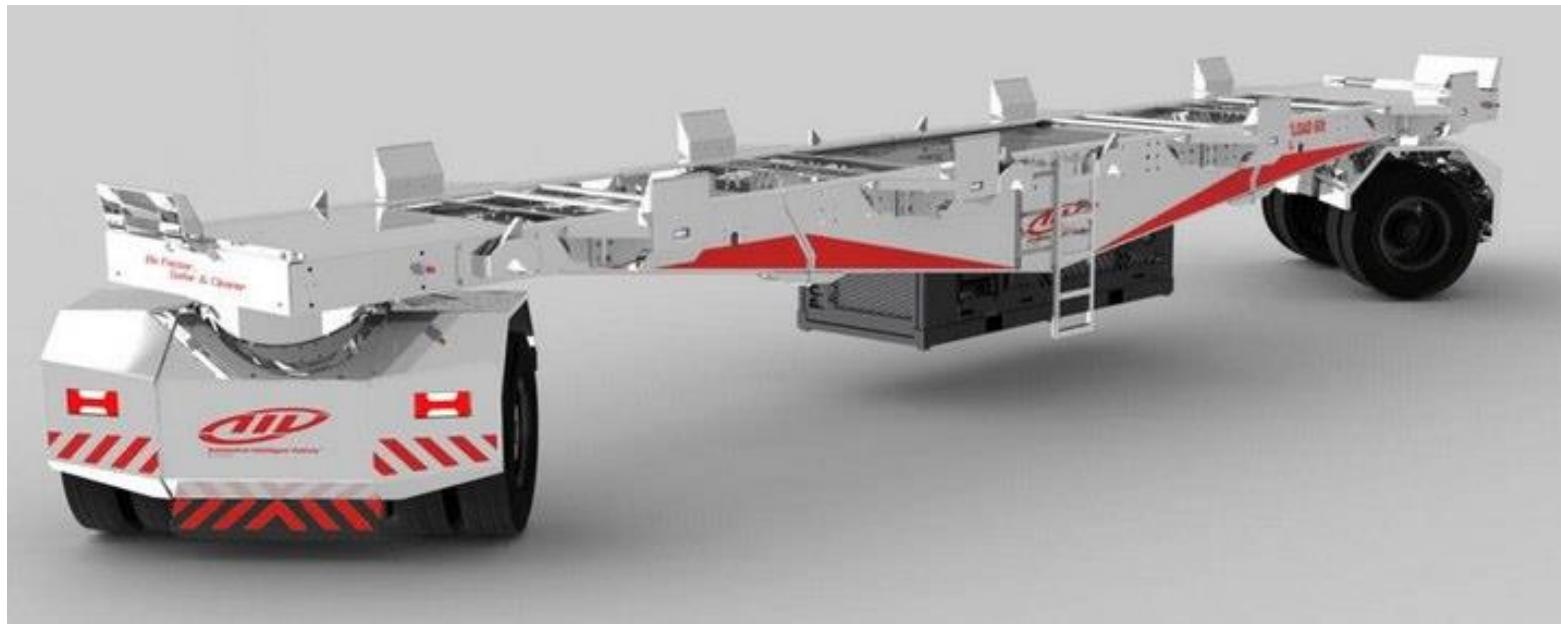


- **Mobile robot to automate animal feeding**
Goats, cows, sheep...

- **From a manual forklift**
Automatisation box directly installed on standard forklift

- **5 partners**
Chambres d'Agriculture de Bretagne, Centrale Nantes, MANITOU Industrie, MEITO, BA Systèmes

ROBOT portuaire

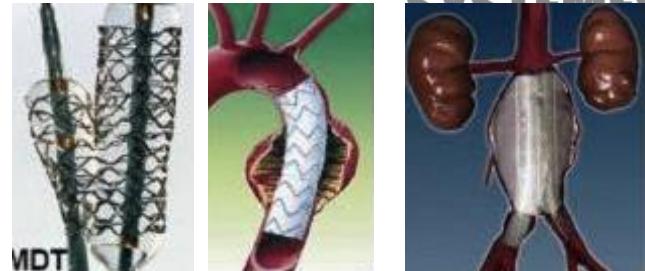


3 – Co développement

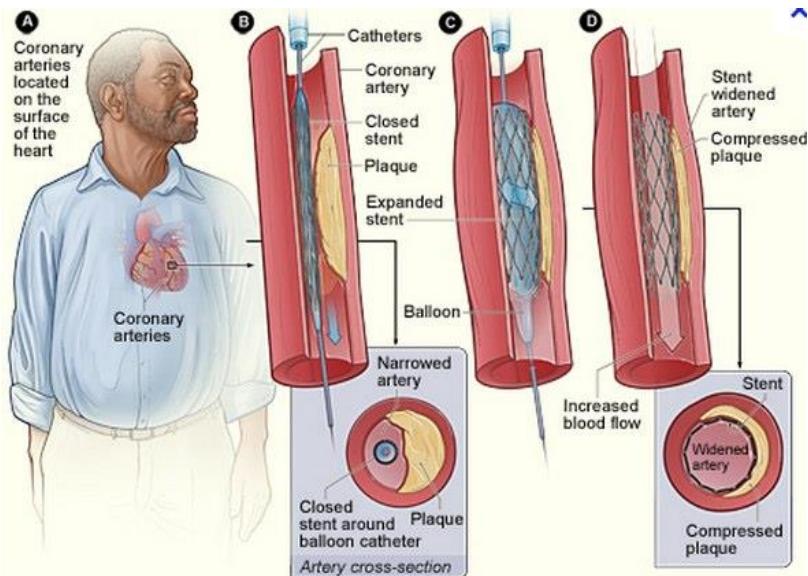
Usage,
Open innovation,
Production & valeurs

Needs of minimally invasive surgery

Necessity to **evaluate** the surgical intervention **in real time** emerges
 Ex : Stenting operations



Surgery operations procedures demand
extremely high precision
 EX : valves implant

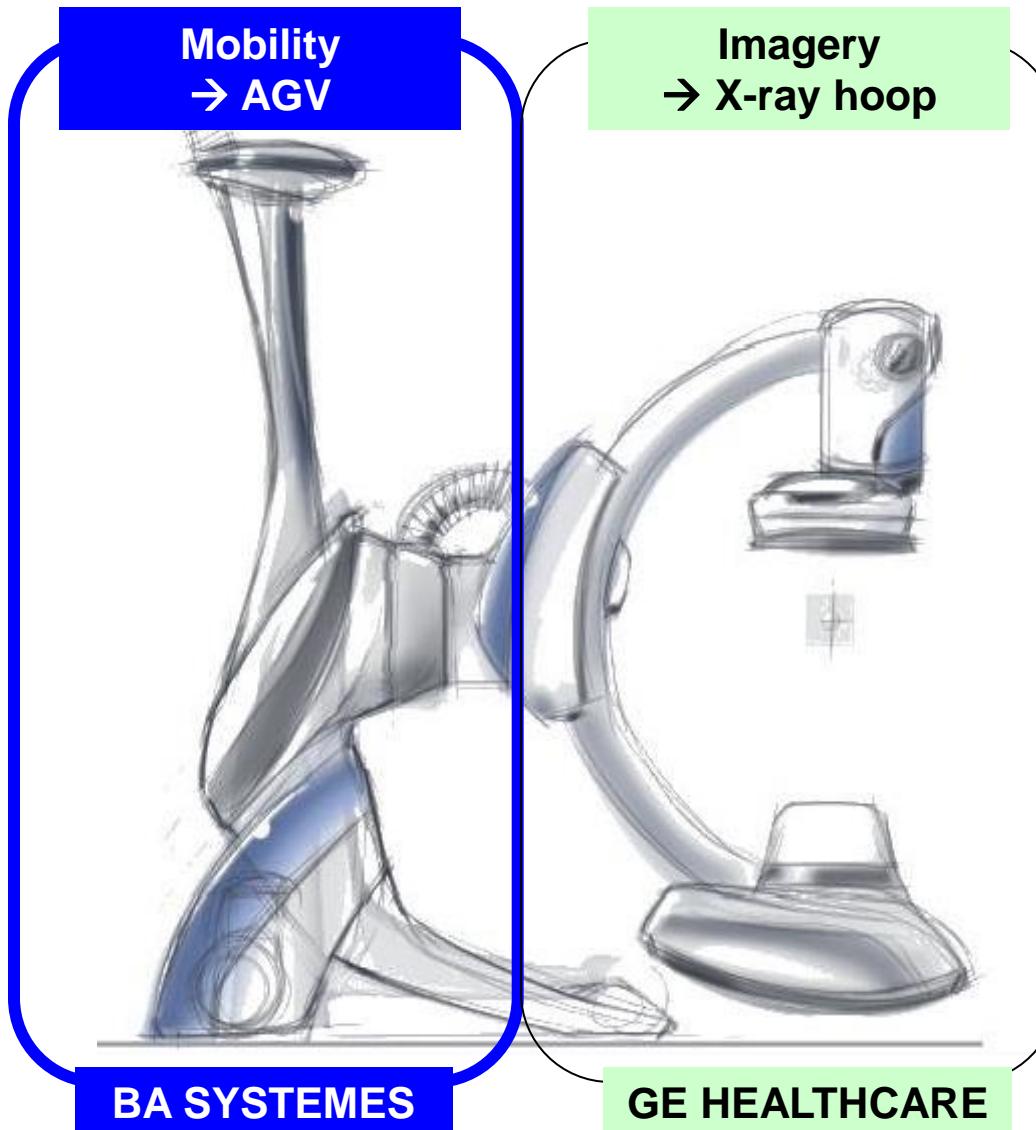


INNOVATION : AGV for imagery in mini-invasive surgery

Navigation
Control
motion
IT Interfaces

Mobility
→ AGV

Imagery
→ X-ray hoop



Imagery chain
C-XRAY
Safety

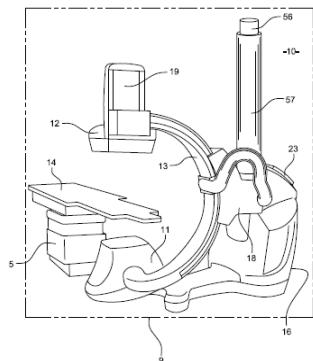
Innovation processus of IRIMI project

Avril 2009 à octobre 2009

Démonstrateur
250 kE



B to B
General Electric
BA Systèmes



Avril 2010 à avril 2012

Projet collaboratif
FUI IRIMI – 18 ME



Zones de test (sans possibilité d'imagerie X)



Salles plombées (possibilité d'imagerie X)



Robot d'essai AGILA

Open innovation

General Electric - BA Systèmes – C&K
IRCCyN (CNRS) – CEA List - INRA - APHP

mars 2011 à Janvier 2012 motion

Industrialisation



B to B
General Electric
BA Systèmes



Construction d'une usine
Création de 20 emplois
(1500 m² en Bretagne)

DISCOVERY IGS 730: The GE project



- **Newest Image Guided System for surgery**
BA Systèmes laser guidance system is accurate within 4 mm
- **GENERAL ELECTRIC chose BA Systemes because:**
 - Time to market decrease:
-3 years, with BA Systèmes
 - No european equivalent
 - Special skills in accurate motion control
- **Creation of a new company:
BA HEALTHCARE**
20 employees hired

4 – Vers de nouveaux usages

ASIMOV Project

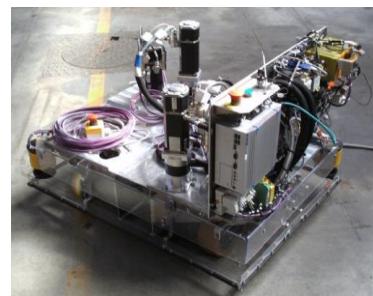
Assistant for Industrial structure and Systems and Manufacturing Optimization Value

Objective: Reducing costs and time of the cycles for assembly and installation of system in final assemble line and major component aircraft

New generation of COBOT for aerospace industry

Length: **43 months**

Budget: **2 M €**



STAMINA Project

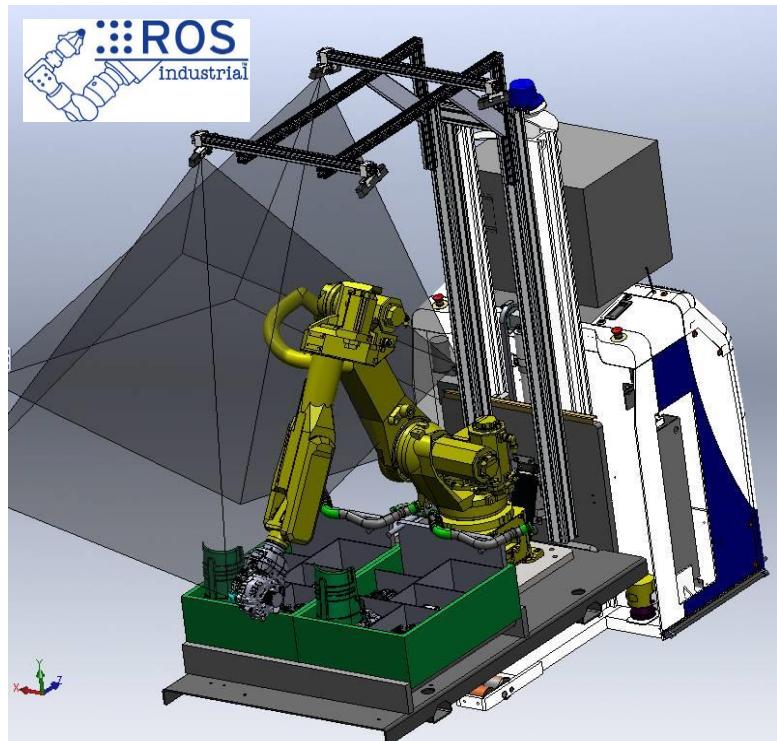


Sustainable and reliable robotics for part handling in manufacturing

to develop a fleet of autonomous and mobile industrial robots with different sensory, planning and physical capabilities

42 months - From October 2013

Total budget **Million € 6.2**

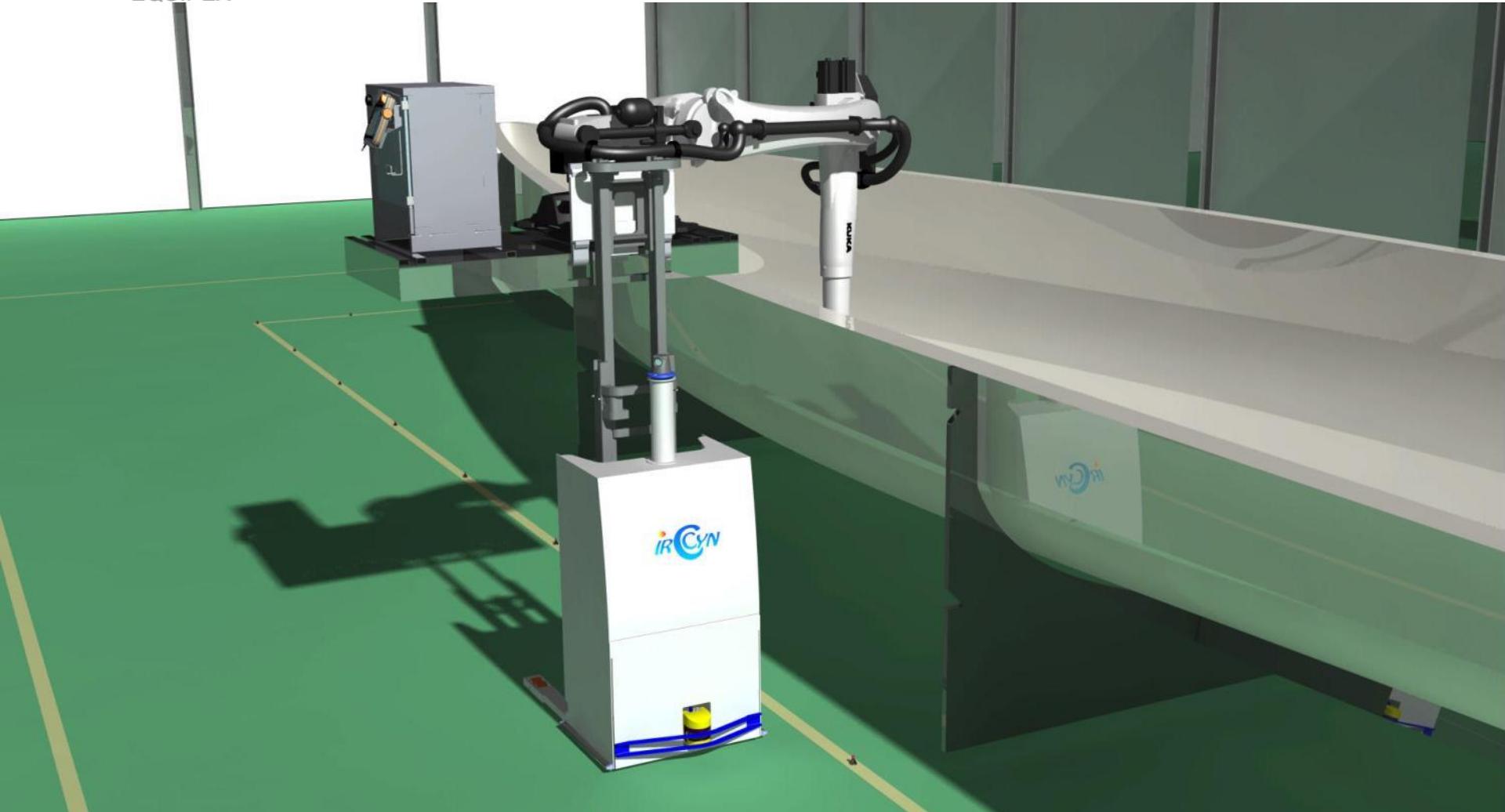


7 European partners

ROBOT pour procédés de fabrication

robotex
EQUIPEX

iRCYN



Conclusion

Conclusion

“Il s'agit d'éclairer les enjeux en mécanique et **technologie** au travers d'approches **pluridisciplinaires**, un des moteurs de l'**innovation**”

■ **Activités industrielles**

Commercial, BE, Usine, service Clients.

Méthodes d'innovation (organisation, RID, CK)

■ **Innovations « pluridisciplinaires » tirées par les usages**

Méthodes de gestion, sciences douces

Diversification, innovation

■ **Liens forts avec les secteurs académiques**

Projets collaboratifs (ANR, FUI, FP7), enseignements, Projets pédagogiques - Implication, compréhension des besoins

■ **Perspectives**

Ouverture internationale, associations

Nouveaux projets en Asie

MERCI DE VOTRE ATTENTION

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